

STRICT COMPLIMENTARY ROOT-BASED ITERATIVE SOLUTION TO THE KEPLER'S EQUATION FOR SATELLITE WITH ELLIPTICAL OR CIRCULAR ORBITS

Israel Sylvester Umana¹

Dept. of Electrical/Electronic & Computer Engineering, University of Uyo, Nigeria

Akpasam Joseph Ekanem²

Department of Electrical and Electronic Engineering, Akwa Ibom State University Mkpat Enin, Akwa Ibom State, Nigeria

Ogungbemi Emmanuel Oluropo³

Dept. of Electrical/Electronic & Computer Engineering, University of Uyo, Nigeria

Abstract— In this paper, strict complimentary root-based iterative solution to the Kepler's equation for satellite with elliptical or circular orbits is presented. Specifically, the approach is used to determine the eccentricity anomaly (E) of the orbit for a given set of values of orbital eccentricity (e) and mean anomaly (M). The performance of the Strict Complementary Root Seeded Secant (SCRSS) Method in computing the eccentricity anomaly of the elliptical or circular orbits is compared with that of fixed point iteration (FPI) method. Both the SCRSS method and the FPI method utilised a single initial guess value of E which in this paper is estimated using a piecewise function which specified the initial guess values for three different range of values of M. The computation of E was implemented with Matlab software. The results of the computation for $e = 0.095$ and $M = 15^\circ$ with error tolerance of $\epsilon \leq 10^{-15}$ show that the FPI converged after 11 cycles whereas the SCRSS converged after 3 cycles. Similarly, the results of the computation for $e = 0.095$ and $M = 45^\circ$ show that the FPI converged after 10 cycles whereas the SCRSS converged after 3 cycles. Furthermore, the results of the computation of E for $e = 0.095$ and values of M ranging from 5° to 75° show that the convergence cycle for the SCRSS algorithm is 3 while that of the FPI algorithm varied from 6 at $M = 75^\circ$ to 13 at $M = 5^\circ$. Again, the results of the computation of E for $e = 0.995$ and values of M ranging from 5° to 75° show that the convergence cycle for the SCRSS algorithm is 4 while that of the FPI algorithm varied from 50 at $M = 75^\circ$ to 71 at $M = 5^\circ$. In all, the SCRSS algorithm converges much faster than the FPI algorithm.

Keywords— *Strict Complimentary Root-Based Iterative , Eccentricity Anomaly , Kepler's Equation , Eccentricity , Satellite Elliptical Orbits, Fixed Point Iteration, Mean Anomaly*

1. Introduction

Over the years, solution of Kepler's equation applicable to different types of satellite orbits has attracted much researches [1,2,3,4,5,6,7,8,9,10]. Mostly, iterative solution approaches are adopted due to the transcendental nature of the equation when the desired parameter is the eccentricity anomaly (E) as a function of the orbit eccentricity (e) and orbit mean anomaly (M) [11,12,13,14,15,16,17,18,19,20]. Again, the fixed point iteration (FPI) has also been widely adopted for this equation due to the FPI method and the fact that only a single initial value is required to perform the FPI algorithm.

However, in many case, the convergence of the FPI method is very poor, hence it requires several iterations before the desired value of E with the requisite accuracy level is

attained [21,22,23,24,25,26]. As such, researchers has resorted to other seeded iteration methods that requires only single initial value for E but with much better convergence performance than the FPI method. According, in this paper, a Strict Complementary Root Seeded Secant (SCRSS) Method is presented and compared with the FPI method [27,28,29]. The SCRSS method requires a single initial guess value for E but converges faster than the FPI method.

Furthermore, in order to further improve on the convergence performance of the iteration methods, a good initial guess value of E is required. As such, in this paper, a piecewise function which specified the initial guess values of E for three different range of values of M is adopted. Finally, the convergence performance of the FPI method and that of the SCRSS method are determined and compared using some numerical examples.

2. Methodology

The Kepler's equation for eccentricity anomaly, E is expressed in terms of the orbital eccentricity and the mean anomaly as follows;

$$E = M + e(\sin(E)) \quad (1)$$

In order to solve the transcendental Kepler's equation for E, iterative solution is usually adopted. In this paper, three different iterative approaches are presented, each with the initial guess value of E denoted as E_0 and as expressed by [30], where;

$$E_0 = \begin{cases} M + ((6M)^{1/3} - M)e^2 & \text{for } 0 \leq M \leq 0.25 \\ M + e \left(\frac{\sin(M)}{1 - \sin(M+e) + \sin(M)} \right) & \text{for } 0.25 \leq M \leq 2 \\ M + e \left(\frac{e(\sin(M))}{\sqrt{(1-2e\cos(M)+e^2)}} \right) & \text{for } 2 \leq M \leq \pi \end{cases} \quad (2)$$

The subsequent values of E are determined through iterative approach with a termination error tolerance, ϵ . The three iterative solutions considered in this paper are: classical secant method, onetime complementary root seeded secant method and strict complementary root seeded secant method.

2.1 The Fixed Point Method

For the fixed point method, one initial guess value of E is required. Let the single initial guess value of E be denoted as E_0 where its value is as define by [30]. Hence, the analytical procedure for defining the fixed iteration method is given as follows;

At the initial cycle, $x = 0$, then;

$$E_x = E_0 = \begin{cases} M + ((6M)^{1/3} - M)e^2 & \text{for } 0 \leq M \leq 0.25 \\ M + e\left(\frac{\sin(M)}{1 - \sin(M+e) + \sin(M)}\right) & \text{for } 0.25 \leq M \leq 2 \\ M + e\left(\frac{e(\sin(M))}{\sqrt{(1-2e\cos(M)+e^2)}}\right) & \text{for } 2 \leq M \leq \pi \end{cases} \quad (3)$$

$$E_{x+1} = M + e(\sin(E_x)) \quad (4)$$

$$f(E_x) = E_x - E_{x+1} \quad (5)$$

If $f(E_x) \leq \epsilon$ then stop otherwise $x = x + 1$ and then repeat the cycle by calculating E_{x+1} and $f(E_x)$ and checking the termination condition $f(E_x) \leq \epsilon$. The fixed iteration algorithm for the computation of E based on the given initial value of E_0 and estimation error, ϵ is as follows;

Step 1: Input M, e, ϵ

Step 2 : $x=0$

Step 3 :

$$E_x = \begin{cases} M + ((6M)^{1/3} - M)e^2 & \text{for } 0 \leq M \leq 0.25 \\ M + e\left(\frac{\sin(M)}{1 - \sin(M+e) + \sin(M)}\right) & \text{for } 0.25 \leq M \leq 2 \\ M + e\left(\frac{e(\sin(M))}{\sqrt{(1-2e\cos(M)+e^2)}}\right) & \text{for } 2 \leq M \leq \pi \end{cases}$$

Step 4 : $E_{x+1} = M + e(\sin(E_x))$

Step 5 : $f(E_x) = E_x - (M + e(\sin(E_x)))$

Step 6 : If $f(E_x) \leq \epsilon$ then goto step 8 else $x = x + 1$;
goto step 4

Step 8 : Output E_{x+1}

Step 9 : End

2.2 Strict Complementary Root Seeded Secant Method

The strict complementary root seeded secant method is defined as follows; at $x=0$

$$E_0 = \begin{cases} M + ((6M)^{1/3} - M)e^2 & \text{for } 0 \leq M \leq 0.25 \\ M + e\left(\frac{\sin(M)}{1 - \sin(M+e) + \sin(M)}\right) & \text{for } 0.25 \leq M \leq 2 \\ M + e\left(\frac{e(\sin(M))}{\sqrt{(1-2e\cos(M)+e^2)}}\right) & \text{for } 2 \leq M \leq \pi \end{cases} \quad (3)$$

$$E_{x+1} = M + e(\sin(E_x)) \quad (4)$$

$$f(E_x) = E_x - E_{x+1} \quad (5)$$

$$f(E_{x+1}) = E_{x+1} - (M + e(\sin(E_{x+1}))) \quad (6)$$

$$E_{x+2} = \frac{E_x(f(E_{x+1})) - E_{x+1}(f(E_x))}{f(E_{x+1}) - f(E_x)} \quad (7)$$

$$f(E_{x+2}) = E_{x+2} - (M + e(\sin(E_{x+2}))) \quad (8)$$

If $f(E_{x+2}) \leq \epsilon$ then stop otherwise $x = x + 1$, $E_x = E_{x+1}$ and then repeat the cycle by calculating E_{x+1} , $f(E_x)$, $f(E_{x+1})$, E_{x+2} , $f(E_{x+2})$ and checking the termination condition $f(E_{x+2}) \leq \epsilon$. The strict complementary root seeded secant algorithm for the computation of E based on the given single initial value of E_x and estimation error, ϵ is as follows;

Step 1: Input M, e, ϵ

Step 2 : $x=0$

Step 3 :

$E_0 =$

$$\begin{cases} M + ((6M)^{1/3} - M)e^2 & \text{for } 0 \leq M \leq 0.25 \\ M + e\left(\frac{\sin(M)}{1 - \sin(M+e) + \sin(M)}\right) & \text{for } 0.25 \leq M \leq 2 \\ M + e\left(\frac{e(\sin(M))}{\sqrt{(1-2e\cos(M)+e^2)}}\right) & \text{for } 2 \leq M \leq \pi \end{cases}$$

Step 4 :

$$E_{x+1} = M + e(\sin(E_x))$$

Step 5 : $f(E_x) = E_x - E_{x+1}$

Step 6 : $f(E_{x+1}) = E_{x+1} - (M + e(\sin(E_{x+1})))$

Step 7 : $E_{x+2} = \frac{E_x(f(E_{x+1})) - E_{x+1}(f(E_x))}{f(E_{x+1}) - f(E_x)}$

Step 8 :

$$f(E_{x+2}) = E_{x+2} - (M + e(\sin(E_{x+2})))$$

Step 9 :

If $f(E_{x+2}) \leq \epsilon$ then goto step 10 else $x = x + 1$; $E_x = E_{x+1}$ goto step 4

Step 10 : Output E_{x+2}

Step 11 : End

3. RESULTS AND DISCUSSION

The computation of E based on Kepler's equation was implemented with Matlab software. The results of the computation using the fixed point iteration (FPI) method for $e = 0.095$ and $M = 15^\circ$ with error tolerance of $\epsilon \leq 10^{-15}$ are presented in Table 1 while Table 2 is the result of Strict Complementary Root Seeded Secant (SCRSS) Method for $e = 0.095$ and $M = 15^\circ$ with error tolerance of $\epsilon \leq 10^{-15}$. The results show that the FPI converged after 11 cycles whereas the SCRSS converged after 3 cycles.

Similarly, the results of the computation using the fixed point iteration (FPI) method for $e = 0.095$ and $M = 45^\circ$ with error tolerance of $\epsilon \leq 10^{-15}$ are presented in Table 3 while Table 4 is the result of Strict Complementary Root Seeded Secant (SCRSS) Method for $e = 0.095$ and $M = 45^\circ$ with error tolerance of $\epsilon \leq 10^{-15}$. The results show that the FPI converged after 10 cycles whereas the SCRSS converged after 3 cycles.

The convergence performance of the two algorithms is demonstrated by computing the value of E for a given e and various values of M. Specifically, the results of the computation of E for $e = 0.095$ and values of M ranging from 5° to 75° are given in Table 5 and Figure 1. The results show that for the given range of values of M, the convergence cycle for the SCRSS algorithm is 3 while that of the FPI algorithm varied from 6 at $M = 75^\circ$ to 13 at $M = 5^\circ$.

Again, the results of the computation of E for $e = 0.995$ and values of M ranging from 5° to 75° are given in Table 6 and Figure 2. The results show that for the given range of values of M, the convergence cycle for the SCRSS algorithm is 4 while that of the FPI algorithm varied from 50 at $M = 75^\circ$ to 71 at $M = 5^\circ$. In all, the SCRSS algorithm converges much faster than the FPI algorithm.

Table 1 Result of the fixed point iteration (FPI) method for $e = 0.095$ and $M = 15^\circ$ with error tolerance of $\varepsilon \leq 10^{-15}$

E = 0.095	M = 15°	M = 0.261799 radians	
	Eo = 16.54888682°	Eo = 0.288833 radians	
Cycle x	Ex	f(Ex)	Ex+1
1	2.888326E-01	-2.60E-05	2.888586E-01
2	2.888586E-01	-2.37E-06	2.888609E-01
3	2.888609E-01	-2.16E-07	2.888611E-01
4	2.888611E-01	-1.96E-08	2.888612E-01
5	2.888612E-01	-1.79E-09	2.888612E-01
6	2.888612E-01	-1.63E-10	2.888612E-01
7	2.888612E-01	-1.48E-11	2.888612E-01
8	2.888612E-01	-1.35E-12	2.888612E-01
9	2.888612E-01	-1.23E-13	2.888612E-01
10	2.888612E-01	-1.12E-14	2.888612E-01
11	2.888612E-01	-9.99E-16	2.888612E-01
12	2.888612E-01	0.00E+00	2.888612E-01

Table 2 Result of the Strict Complementary Root Seeded Secant (SCRSS) Method for $e = 0.095$ and $M = 15^\circ$

E = 0.095	M = 15°	M = 0.261799 radians	Eo = 16.54888682°	Eo = 0.288833 radians		
Cycle x	Ex	f(Ex)	Ex+1	f(Ex+1)	Ex+2	f(Ex+2)
1	2.888326E-01	-2.60E-05	2.888586E-01	2.89E-01	2.888612E-01	1.01E-12
2	2.888612E-01	1.01E-12	2.888612E-01	2.89E-01	2.888612E-01	0.00E+00
3	2.888612E-01	0.00E+00	2.888612E-01	2.89E-01		

Table 3 Result of the fixed point iteration (FPI) method for $e = 0.095$ and $M = 45^\circ$

E = 0.095	M = 45°	M = 0.785398 radians	
	Eo = 49.11151967 °	Eo = 0.857158 radians	
Cycle x	Ex	f(Ex)	Ex+1
1	8.571577E-01	-5.90E-05	8.572167E-01
2	8.572167E-01	-3.67E-06	8.572204E-01
3	8.572204E-01	-2.28E-07	8.572206E-01
4	8.572206E-01	-1.42E-08	8.572207E-01
5	8.572207E-01	-8.83E-10	8.572207E-01
6	8.572207E-01	-5.49E-11	8.572207E-01
7	8.572207E-01	-3.41E-12	8.572207E-01
8	8.572207E-01	-2.12E-13	8.572207E-01
9	8.572207E-01	-1.31E-14	8.572207E-01
10	8.572207E-01	-8.88E-16	8.572207E-01
11	8.572207E-01	0.00E+00	8.572207E-01

Table 4 Result of the Strict Complementary Root Seeded Secant (SCRSS) Method for $e = 0.095$ and $M = 45^\circ$

$E = 0.095$	$M = 45^\circ$	$M = 0.785398$ radians	$E_0 = 49.11151967$ °	$E_0 = 0.857158$ radians		
Cycle x	E_x	$f(E_x)$	E_{x+1}	$f(E_{x+1})$	E_{x+2}	$f(E_{x+2})$
1	8.571577E-01	-5.90E-05	8.572167E-01	8.57E-01	8.572207E-01	8.85E-12
2	8.572207E-01	8.85E-12	8.572207E-01	8.57E-01	8.572207E-01	0.00E+00
3	8.572207E-01	0.00E+00	8.572207E-01	8.57E-01	#DIV/0!	#DIV/0!

Table 5 Convergence Cycle (n) for the cases where $e = 0.095$

e	M in degrees	E_0 in degree	E_{in} degrees	Convergence Cycle (n) for FPI Method	Convergence Cycle (n) for SCRSS Method	P% Reduction in convergence cycle
0.095	5	5.371651	5.524	13	3	76.9
0.095	15	16.54889	16.5505	11	3	72.7
0.095	25	27.51148	27.5146	11	3	72.7
0.095	45	49.11152	49.1151	10	3	70.0
0.095	55	59.69693	59.6995	9	3	66.7
0.095	75	80.366	80.3663	6	3	50.0
Average				10	3	70.0

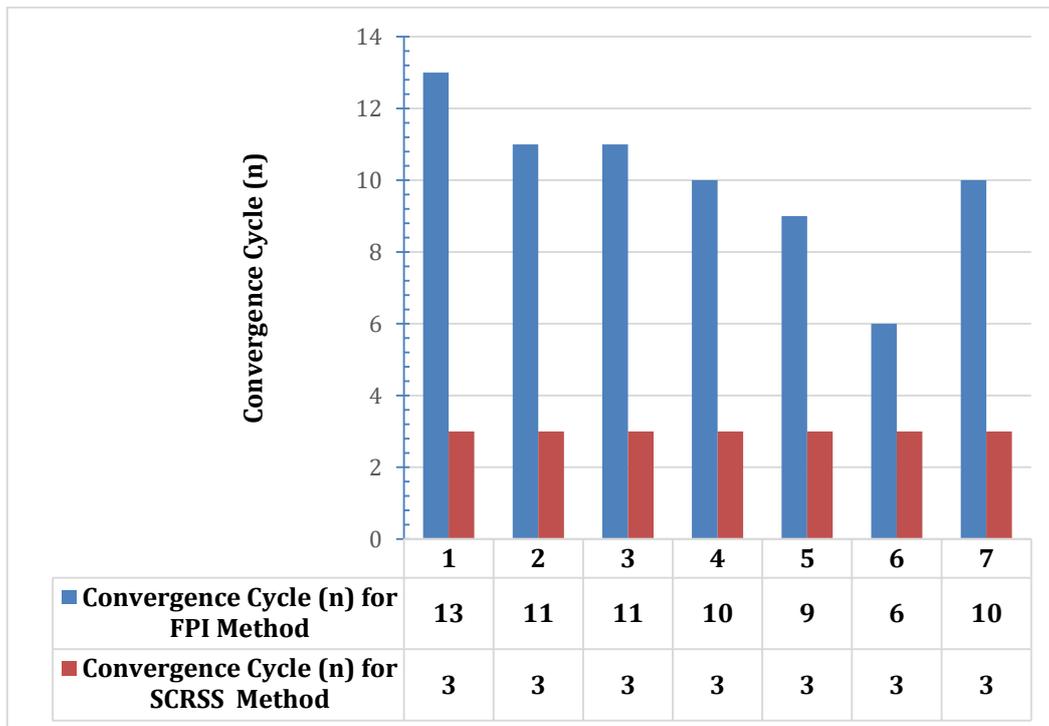


Figure 1 Convergence Cycle (n) for the cases where $e = 0.095$

Table 6 Convergence Cycle (n) for the cases where e = 0.995

e	M in degrees	Eo in degree	Ein degrees	Convergence Cycle (n) for FPI Method	Convergence Cycle (n) for SCRSS Method	P% Reduction in convergence cycle
0.995	5	45.7694	46.0293	71	4	94.4
0.995	15	62.95092	67.7731	32	5	84.4
0.995	25	80.72897	81.3628	16	4	75.0
0.995	45	100.2977	100.968	18	4	77.8
0.995	55	107.3518	108.927	27	4	85.2
0.995	75	120.03	122.878	50	4	92.0
Average				35.7	4.2	88.3

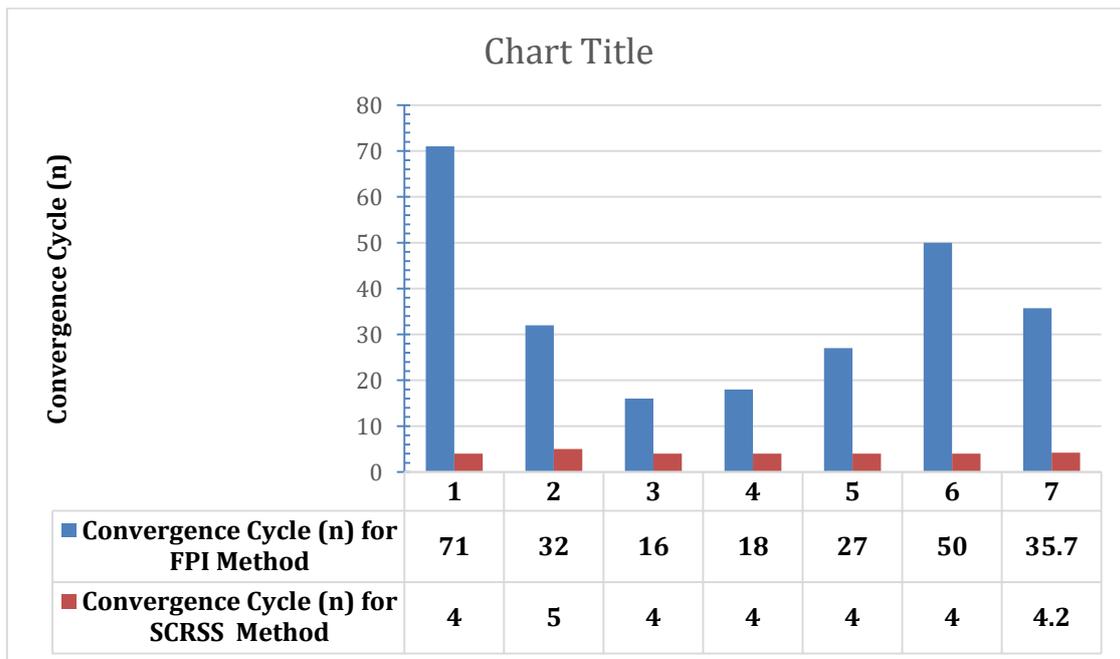


Figure 2 Convergence Cycle (n) for the cases where e = 0.995

4.0 CONCLUSION

A seeded secant approach for computing the eccentricity anomaly for satellites with elliptical or circular orbits is presented. The approach used complementary-root form of the Kepler's equation in similar way are is applicable to the popular fixed iteration method. Hence, the convergence performance of the Strict Complementary Root Seeded Secant (SCRSS) Method is compared with that of the fixed point iteration (FPI) method. In all, the results showed that in the computation of the eccentricity anomaly for elliptical and circular orbits, the SCRSS method converged much faster than the FPI method in all the cases considered.

REFERENCE

1. Capderou, M. (2014). *Handbook of satellite orbits: From kepler to GPS*. Springer Science & Business.
2. Roy, A. E. (2020). *Orbital motion*. CRC Press.
3. RASHEED, M., Alabdali, O., SHIHAB, S., & RASHID, T. (2021). Evaluation and Determination of the Parameters of a Photovoltaic Cell by an Iterative Method. *Journal of Al-Qadisiyah for Computer Science and Mathematics*, 13(1), Page-34.
4. Kiani, M. (2020). Simultaneous approximation of a function and its derivatives by Sobolev polynomials: Applications in satellite geodesy and precise orbit determination for LEO

- CubeSats. *Geodesy and Geodynamics*, 11(5), 376-390.
5. Gurfil, P., & Lara, M. (2014). Satellite onboard orbit propagation using Deprit's radial intermediary. *Celestial Mechanics and Dynamical Astronomy*, 120(2), 217-232.
 6. Ibrahim, R. H., & Saleh, A. R. H. (2020, December). A comparison between Runge-Kutta and Adams-Bashforth methods for determining the stability of the satellite's orbit. In *AIP Conference Proceedings* (Vol. 2290, No. 1, p. 050002). AIP Publishing LLC.
 7. Ye, S., Chen, D., Liu, Y., Jiang, P., Tang, W., & Xia, P. (2015). Carrier phase multipath mitigation for BeiDou navigation satellite system. *GPS solutions*, 19(4), 545-557.
 8. Musielak, Z. E., & Quarles, B. (2014). The three-body problem. *Reports on Progress in Physics*, 77(6), 065901.
 9. Rasheed, M. S., & Sarhan, M. A. (2019). Measuring the Solar Cell Parameters Using Fuzzy Set Technique. *Insight-Electronic*, 1(1).
 10. Gkolias, I., Daquin, J., Gachet, F., & Rosengren, A. J. (2016). From order to chaos in Earth satellite orbits. *The Astronomical Journal*, 152(5), 119.
 11. González-Gaxiola, O., & Hernández-Linares, S. (2021). An Efficient Iterative Method for Solving the Elliptical Kepler's Equation. *International Journal of Applied and Computational Mathematics*, 7(2), 1-14.
 12. Desai, R., Patel, P., Shah, D., Shah, D., Sahni, M., & Sahni, R. (2021). Development and Application of the DMS Iterative Method Having Third Order of Convergence. In *Mathematical Modeling, Computational Intelligence Techniques and Renewable Energy: Proceedings of the First International Conference, MMCITRE 2020* (pp. 55-63). Springer Singapore.
 13. Antonana, M., Makazaga, J., & Murua, A. (2017). Reducing and monitoring round-off error propagation for symplectic implicit Runge-Kutta schemes. *Numerical Algorithms*, 76(4), 861-880.
 14. Raposo-Pulido, V., & Peláez, J. (2018). An efficient code to solve the Kepler equation-Hyperbolic case. *Astronomy & Astrophysics*, 619, A129.
 15. Philcox, O. H. E., Goodman, J., & Slepian, Z. (2021). Kepler's Goat Herd: An Exact Solution to Kepler's Equation for Elliptical Orbits. *Monthly Notices of the Royal Astronomical Society*.
 16. Sharaf, M. A., & Hendi, F. A. HOMOTOPY CONTINUATION METHOD OF ARBITRARY ORDER OF CONVERGENCE FOR SOLVING DIFFERENCED HYPERBOLIC KEPLER'S EQUATION. *Journal: JOURNAL OF ADVANCES IN MATHEMATICS*, 10(5).
 17. Tommasini, D., & Olivieri, D. N. (2021). Comment on" An efficient code to solve the Kepler equation. Elliptic case". *arXiv preprint arXiv:2105.13009*.
 18. Mathar, R. J. Improved First Estimates to the Solution of Kepler's Equation.
 19. Bucur, A. (2017). ABOUT APPLICATIONS OF THE FIXED POINT THEORY. *Scientific Bulletin-Nicolae Balcescu Land Forces Academy*, 22(1), 13-17.
 20. Chen, B., Liu, X., Zhao, H., & Principe, J. C. (2017). Maximum correntropy Kalman filter. *Automatica*, 76, 70-77.
 21. Chan, S. H., Wang, X., & Elgendy, O. A. (2016). Plug-and-play ADMM for image restoration: Fixed-point convergence and applications. *IEEE Transactions on Computational Imaging*, 3(1), 84-98.
 22. Chen, M., Poor, H. V., Saad, W., & Cui, S. (2020). Convergence time optimization for federated learning over wireless networks. *IEEE Transactions on Wireless Communications*, 20(4), 2457-2471.
 23. Ahmad, M. S., Ali, A., Tanveer, M., Aslam, A., & Nazeer, W. (2015). New fixed point iterative method for solving nonlinear functional equations. *Sci. Int.(Lahore)*, 27(3), 1815-1817.
 24. Ali, A., Ahmad, M. S., Tanveer, M., Mehmood, Q., & Nazeer, W. (2015). Modified two-step fixed point iterative method for solving nonlinear functional equations. *Sci. Int.(Lahore)*, 27(3), 1737-1739.
 25. Gemechu, T., & Thota, S. (2020). On new root finding algorithms for solving nonlinear transcendental equations. *International Journal of Chemistry, Mathematics and Physics*, 4(2), 18-24.
 26. Nazeer, W., Kang, S. M., Tanveer, M., & Shahid, A. A. (2015). Modified Two-step Fixed Point Iterative Method for Solving Nonlinear Functional Equations with Convergence of Order Five and Efficiency Index 2.2361. *Wulfenia Journal*, 22(5), 24-32.
 27. Iganatius, E. J., Livinus, E. N., & Stephen, B. U. A. Applied Residue-Based Seeded Secant Method For Computing Eccentricity of Normal Ellipsoid.
 28. Simeon, O.(2015) Analysis Of Perturbance Coefficient-Based Seeded Secant Iteration Method. Vol. 2 Issue 1, January - 2015
 29. Simeon, O. (2017). Development Of Strict Differential Seeded Secant Numerical Iteration Method For Computing The Semi Major Axis Of A Perturbed Orbit Based On The Anomalistic Period. *Development*, 1(8).
 30. Esmaelzadeh, R., & Ghadiri, H. (2014). Appropriate starter for solving the Kepler's equation. *International Journal of Computer Applications*, 975, 8887.